

- ① Lecture 1: gravitational wave astronomy, the two-body problem, and self-force theory
- ② Lecture 2: the local problem: how to deal with small bodies
- ③ Lecture 3: the global problem: orbital dynamics in Kerr
  - Geodesic motion in Kerr
  - Perturbed motion in Kerr
  - Transient resonances
- ④ Lecture 4: the global problem: black hole perturbation theory

# Solving the Einstein equations globally

- solving the local problem told us how to replace the small object with a moving puncture in the field equations:

$$G_{\mu\nu}^{(1)}[h^{\mathcal{R}(1)}] = -G_{\mu\nu}^{(1)}[h^{\mathcal{P}(1)}]$$

$$G_{\mu\nu}^{(1)}[h^{\mathcal{R}(2)}] = -G_{\mu\nu}^{(2)}[h^{(1)}, h^{(1)}] - G_{\mu\nu}^{(1)}[h^{\mathcal{P}(2)}]$$

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2}(g^{\mu\nu} + u^\mu u^\nu)(g_\nu^\delta - h_\nu^{\mathcal{R}\delta})(2h_{\delta\beta;\gamma}^{\mathcal{R}} - h_{\beta\gamma;\delta}^{\mathcal{R}})u^\beta u^\gamma$$

where  $G_{\mu\nu}^{(1)}[h] \sim \square h_{\mu\nu}$ ,  $G_{\mu\nu}^{(2)}[h, h] \sim \nabla h \nabla h + h \nabla \nabla h$

- the global problem: how do we solve these equations in practice in a particular background?

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Kerr metric in Boyer-Lindquist coordinates:

$$ds^2 = - \left( 1 - \frac{2Mr}{\Sigma} \right) dt^2 - \frac{4aMr \sin^2 \theta}{\Sigma} dt d\phi + \frac{\Sigma}{\Delta} dr^2 + \Sigma d\theta^2 \\ + \left[ \Delta + \frac{2Mr(r^2 + a^2)}{\Sigma} \right] \sin^2 \theta d\phi^2$$

$$\Sigma := r^2 + a^2 \cos^2 \theta \quad \text{and} \quad \Delta := r^2 - 2Mr + a^2$$

Symmetries:

- two Killing vectors  $\xi_{(t)}^\alpha = \delta_t^\alpha$  and  $\xi_{(\phi)}^\alpha = \delta_\phi^\alpha$   $(\nabla_{(\alpha} \xi_{\beta)} = 0)$
- one Killing tensor  $K_{\alpha\beta}$   $(\nabla_{(\alpha} K_{\beta\gamma)} = 0)$

# Geodesic motion is integrable [Carter]

- three constants of geodesic motion:  $E = -u_\alpha \xi_{(t)}^\alpha$ ,  $L_z = u_\alpha \xi_{(\phi)}^\alpha$ , and the *Carter constant*  $C = u^\alpha u^\beta K_{\alpha\beta}$ . Also normalization  $g^{\alpha\beta} u_\alpha u_\beta = -1$
- can invert these four equations to obtain  $u^\alpha(r, \theta, E, L_z, C)$ :

$$\Sigma^2 \left( \frac{dr}{d\tau} \right)^2 = R(r)$$

$$\Sigma^2 \left( \frac{dz}{d\tau} \right)^2 = Z(z)$$

$$\Sigma \frac{dt}{d\tau} = T_r(r) + T_z(z) + aL_z := \omega_t(r, z)$$

$$\Sigma \frac{d\phi}{d\tau} = \Phi_r(r) + \Phi_z(z) - aE := \omega_\phi(r, z)$$

orbital inclination  $z := \cos \theta$

- radial and polar motion oscillate between turning points:

$$R(r) = -(1 - E^2)(r - r_1)(r - r_2)(r - r_3)(r - r_4)$$

$$Z(z) = a^2(1 - E^2)(z^2 - z_1^2)(z^2 - z_2^2)$$

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# Decoupling the $r$ - $\theta$ motion

$r(\tau)$  and  $z(\tau)$  are immediately decoupled by adopting *Mino time* as parameter:

$$\frac{d\lambda}{d\tau} = \Sigma^{-1}$$

$$\Rightarrow \left(\frac{dr}{d\lambda}\right)^2 = R(r)$$

$$\left(\frac{dz}{d\lambda}\right)^2 = Z(z)$$

$$\frac{dt}{d\lambda} = \omega_t(r, z)$$

$$\frac{d\phi}{d\lambda} = \omega_\phi(r, z).$$



- manifestly periodic parametrizations:

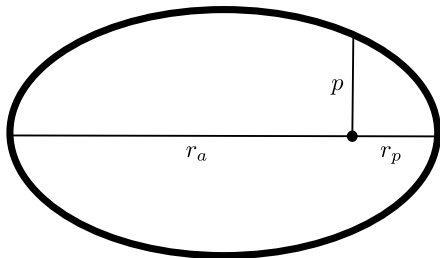
$$r(\psi_r) = \frac{pM}{1 + e \cos \psi_r}$$
$$z(\psi_z) = z_{\max} \cos \psi_z$$

with

$$\frac{d\psi_r}{d\lambda} = \omega_r(\psi_r) \quad \text{and} \quad \frac{d\psi_z}{d\lambda} = \omega_z(\psi_z)$$

- $\{p, e, z_{\max}\} \leftrightarrow \{E, L_z, Q\}$
- $\{p, e, z_{\max}\}$  describe “shape”:

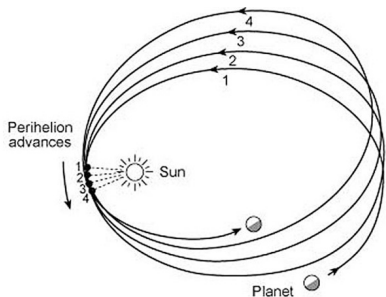
$$r_p = \frac{pM}{1 + e} \quad \text{and} \quad r_a = \frac{pM}{1 - e}$$



# Precession of periapsis

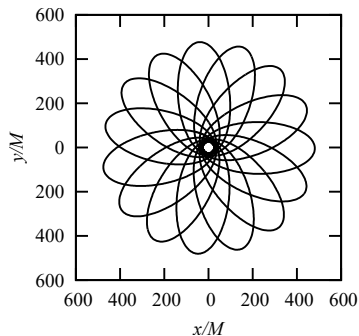
$r$  and  $\phi$  periods are (generically) incommensurate  
 $\Rightarrow$  orbit does not come back to itself

mild planar orbit



[image credit: K. R. Lang]

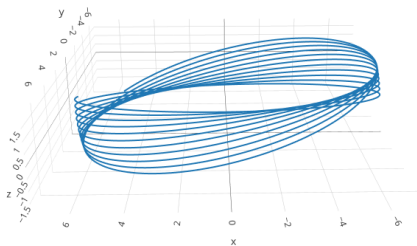
extreme planar orbit



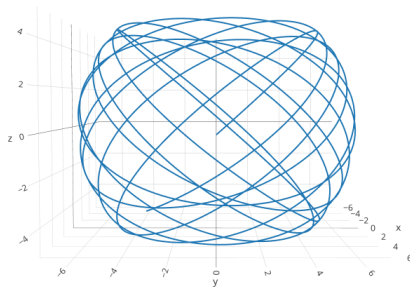
# Precession of orbital plane

$z$  and  $\phi$  periods are (generically) incommensurate

mild spherical orbit

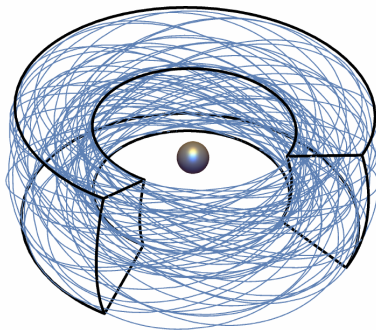


extreme spherical orbit



# Orbits are generically space-filling

$r$  and  $z$  periods are (generically) incommensurate



Generate orbits yourself:

- [http://nielswarburton.net/geodesics/interactive/Kerr\\_geodesic.html](http://nielswarburton.net/geodesics/interactive/Kerr_geodesic.html)
- <https://bhptoolkit.org/KerrGeodesics/>

- Let  $\psi_\alpha = (t, \psi_r, \psi_z, \phi)$  and  $J^\alpha = (p, e, z_{\max})$

$$\begin{aligned}\Rightarrow \frac{d\psi_\alpha}{d\lambda} &= \omega_\alpha(\psi_r, \psi_z) \\ \frac{dJ^\alpha}{d\lambda} &= 0\end{aligned}$$

- Better:  $(\psi_\alpha, J^\alpha) \rightarrow (q_\alpha, J^\alpha)$  such that

$$\begin{aligned}\frac{dq_\alpha}{d\lambda} &= \Upsilon_\alpha(J^\beta) \\ \frac{dJ^\alpha}{d\lambda} &= 0\end{aligned}$$

- $q_\alpha$  is “averaged”  $\psi_\alpha$ :  $\Upsilon_\alpha = \langle \omega_\alpha \rangle_\lambda = \lim_{\Lambda \rightarrow \infty} \frac{1}{2\Lambda} \int_{-\Lambda}^{\Lambda} \omega_\alpha d\lambda$
- $z^\alpha(q_\beta, J^\beta)$  known analytically in terms of Jacobi elliptic functions

- $q_\alpha$  oscillate wrt Boyer-Lindquist  $t$ . Bad for field equations.
- Better:  $(q_\alpha, J^\alpha) \rightarrow (\varphi_A, J^A)$  such that

$$\frac{d\varphi_A}{dt} = \Omega_A(J^B)$$
$$\frac{dJ^A}{dt} = 0$$

- $\varphi_A = (\varphi_r, \varphi_z, \varphi_\phi)$ ,  $J^A = (p, e, z_{\max})$
- $\Omega_A = \frac{\Upsilon_A}{\Upsilon_t}$

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# Perturbed equations of motion in terms of action angles

- $\frac{D^2 z^\alpha}{d\tau^2} = \epsilon F_{(1)}^\alpha + \epsilon^2 F_{(2)}^\alpha + O(\epsilon^3)$
- If we keep fixed the relationship  $(z^\alpha, u_\alpha) \rightarrow (\varphi_A, J^A)$ , then

$$\frac{d\varphi_A}{dt} = \Omega_A^{(0)}(J^B) + \epsilon \Omega_A^{(1)}(J^B, \varphi_B) + O(\epsilon^2)$$

$$\frac{dJ^A}{dt} = \epsilon G_{(1)}^A(J^B, \varphi_B) + \epsilon^2 G_{(2)}^A(J^B, \varphi_B) + O(\epsilon^3)$$



# Perturbed equations in terms of deformed action angles

[van de Meent and Warburton, Pound and Wardell]

- oscillations all over the place
- Better:  $(\varphi_A, J^A) \rightarrow (\tilde{\varphi}_A, \tilde{J}^A)$  such that

$$\begin{aligned}\frac{d\tilde{\varphi}_A}{dt} &= \Omega_A(\tilde{J}^B) \\ \frac{d\tilde{J}^A}{dt} &= \epsilon \tilde{G}_{(1)}^A(J^B) + \epsilon^2 \tilde{G}_{(2)}^A(J^B) + O(\epsilon^3)\end{aligned}$$

- Let  $\tilde{t} = \epsilon t$ . Equations admit asymptotic solution

$$\begin{aligned}\tilde{\varphi}_A(\tilde{t}, \epsilon) &= \frac{1}{\epsilon} \left[ \tilde{\varphi}_A^{(0)}(\tilde{t}) + \epsilon \tilde{\varphi}_A^{(1)}(\tilde{t}) + O(\epsilon^2) \right] \\ \tilde{J}^A(\tilde{t}, \epsilon) &= \tilde{J}_{(0)}^A(\tilde{t}) + \epsilon \tilde{J}_{(1)}^A(\tilde{t}) + O(\epsilon^2)\end{aligned}$$

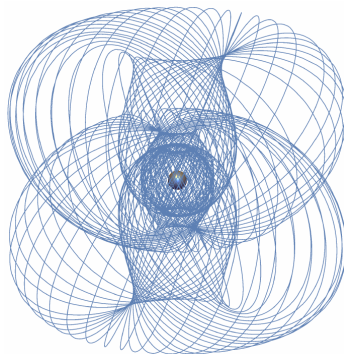
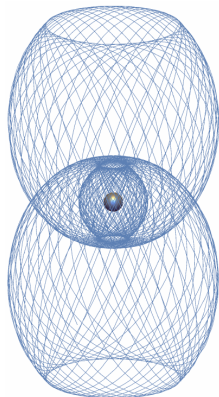
- 0PA and 1PA terms dictated by dissipative and conservative pieces of  $F_{(n)}^\alpha$  as per Hinderer and Flanagan

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# Orbital resonances

- orbital frequencies can be commensurate: e.g., rational  $\Omega_z/\Omega_r$
- shape of orbit strongly depends on relative  $\varphi_r - \varphi_z$  initial phase

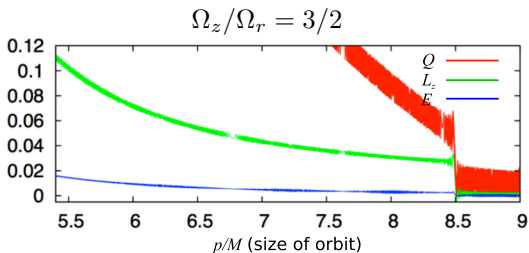
$$\Omega_z/\Omega_r = 3/2$$



# Passage through resonance [Hinderer and Flanagan]

- passage takes time  $\Delta t \sim 1/\sqrt{\epsilon}$ 
  - $\Rightarrow$  frequencies change by  $\Delta\Omega_A \sim \sqrt{\epsilon}$
  - $\Rightarrow$  causes cumulative shift  $\Delta\varphi_A \sim 1/\sqrt{\epsilon}$  by end of inspiral
- new form of solution:

$$\tilde{\varphi}_A(\tilde{t}, \epsilon) = \frac{1}{\epsilon} \left[ \tilde{\varphi}_A^{(0)}(\tilde{t}) + \sqrt{\epsilon} \tilde{\varphi}_A^{(1/2)}(\tilde{t}) + \epsilon \tilde{\varphi}_A^{(1)}(\tilde{t}) + O(\epsilon^{3/2}) \right]$$
$$\tilde{J}^A(\tilde{t}, \epsilon) = \tilde{J}_{(0)}^A(\tilde{t}) + \sqrt{\epsilon} \tilde{J}_{(1/2)}^A(\tilde{t}) + \epsilon \tilde{J}_{(1)}^A(\tilde{t}) + O(\epsilon^2)$$



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